

**Amendments to the Specification:**

Please replace paragraph [0045] with the following:

[0045] The operation of the claimed invention will now be described. After the components for the lowest level of the elevator support structure are installed upon the foundation, the motor drive 30 is powered on. The teeth of the drive gear 61 engage the holes 43 in counterweight guide 22 and the machine begins to climb along the counterweight guide rails 22 and 22'. As discussed above, the shoes 48 on the machine frame 35 guide the machine 30 along the counterweight guide rails 22 and 22', and the guide shoe machine mount assembly 77 prevents the machine from disengaging from holes 43 in guide rail 22. As illustrated in Figure 13, when the motor drive 31 rises, so do the car sling 80 and the temporary platform 91.

Please replace paragraph [0048] with the following:

[0048] As seen in FIGS. 14 and 15, the header module 40 affixed to the top of the support structure generally comprises one or more suspension sheaves, and the support rope 89 passes over the suspension sheave(s) to support the elevator car assembly 81 and the counterweight assembly 91. The rope 89 is driven by the motor drive 31 to move the elevator car assembly 81 and the counterweight assembly 91 within the hoistway.

Please replace paragraph [0049] with the following:

[0049] In FIGS. 14 and 15, the elevator car assembly is mounted to slide along the car guide rails and has a front portion with guide shoes slidably coupled to the car guide rails 7 and 7'. Similarly, the counterweight assembly 91 is mounted to slide along the counterweight guide rails 22 and 22' and has guide shoes slidably coupled to the counterweight guide rails 22 and 22'. The elevator car assembly 81 can be of a car sling type. The elevator car assembly 81 can comprise a pick-up point assembly 85 located above the center of mass of the elevator car assembly 81 for engagement with the support rope 89. The pick-up assembly 85 may comprise a sheave for engagement with the support rope 89.

Please replace paragraph [0050] with the following:

[0050] The motor drive 30 may be affixed to the pit channel module 16 or directly to the foundation of the building. The motor drive 30 can comprise a drive sheave for frictionally engaging the rope 89, or the motor drive 30 can directly drive the rope 89. In either case, the motor drive 30 moves the rope 89, which in turn displaces the elevator car or sling 81 and counterweight 91. As discussed previously, the motor drive 30 used to drive the support rope 89 may be the same motor drive used during self-climbing mode, or it may be a different motor drive.